

# A comparison between mixed and transform data assimilation schemes on short-, medium- and long-term forecasts



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# Introduction

Operational forecast centers are starting to rely heavily upon data assimilation in order to produce more accurate forecasts that are based on current observations. As of present, the transform scheme is used most widely. It minimizes the cost function with respect to ln(x), as opposed to x, and then changes it back to the x space to complete the new forward run. It also takes the observations and considers them to be in the ln(x) space.

Fletcher and Zupanski (2006,2007) have developed the mixed DA system in which the minimzation as well as the observations are kept in the x space. With this, there is no need to convert into a different space, thus retaining more information which is used to produce a, in theory, more accurate forecast.

We will compare the two schemes at varying lengths of forecasts to determine if one produces more correct forecasts than the other and if so, by what magnitude.

# Objective and Methodology

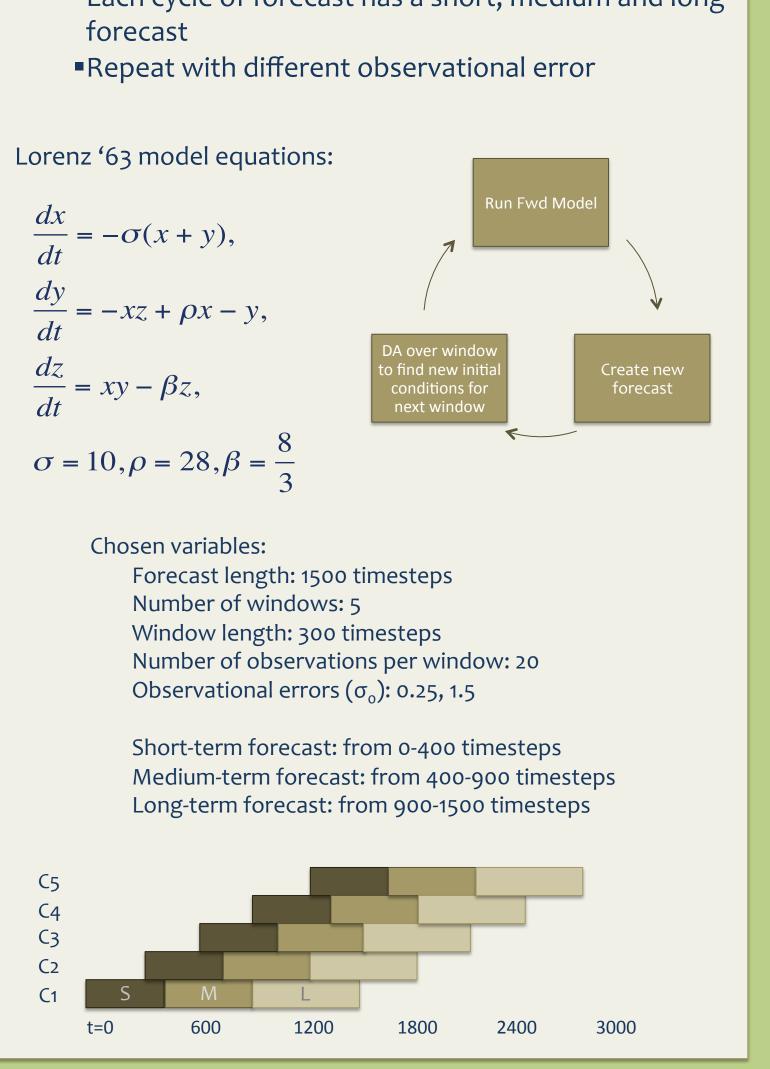
This study was conducted to evaluate which data assimilation scheme is more accurate when producing short-, medium- and long-term forecasts.

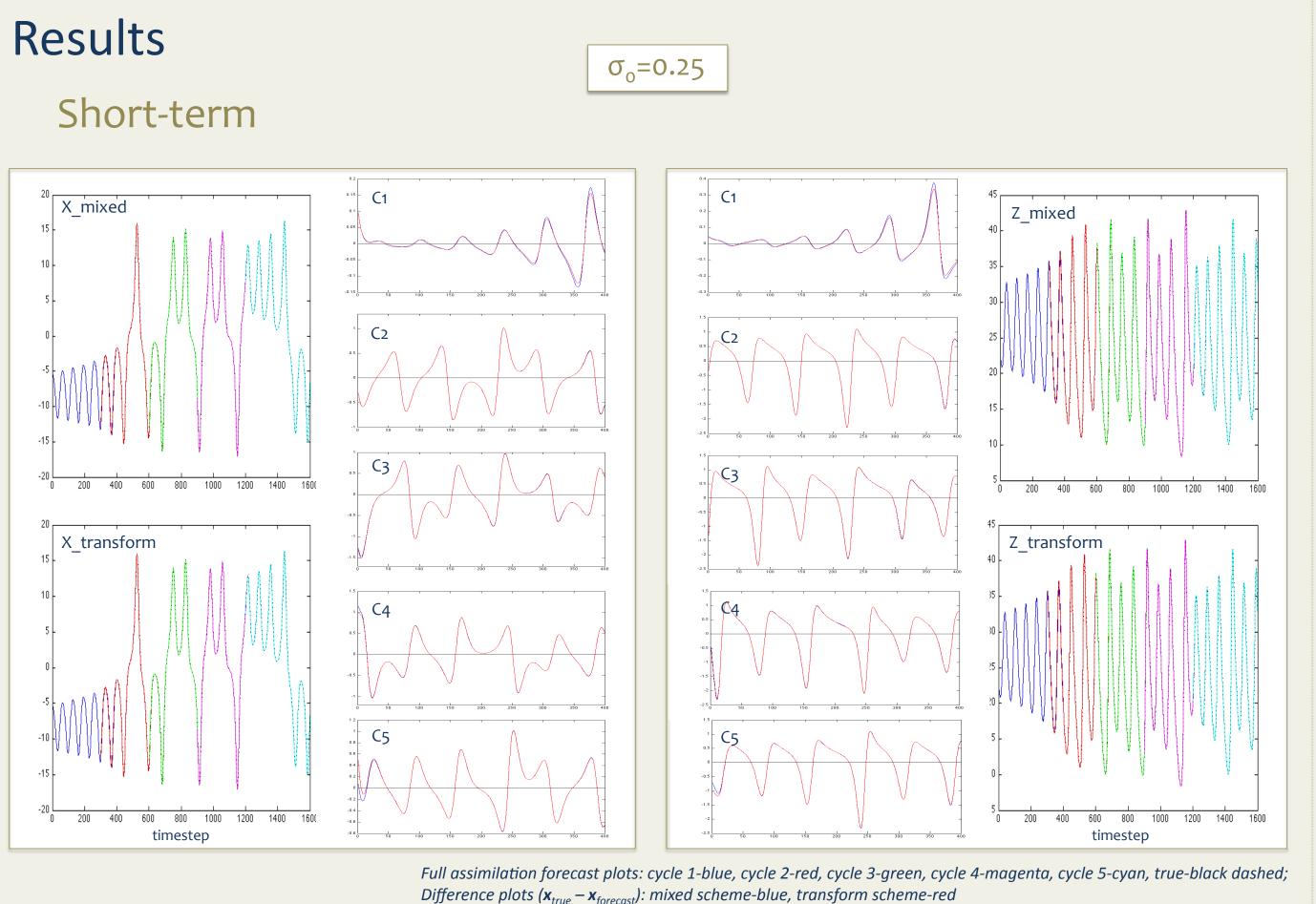
Run Fletcher's 4DVAR data assimilation code for MatLab, on Apple desktop during summer 2010 internship at CMMAP

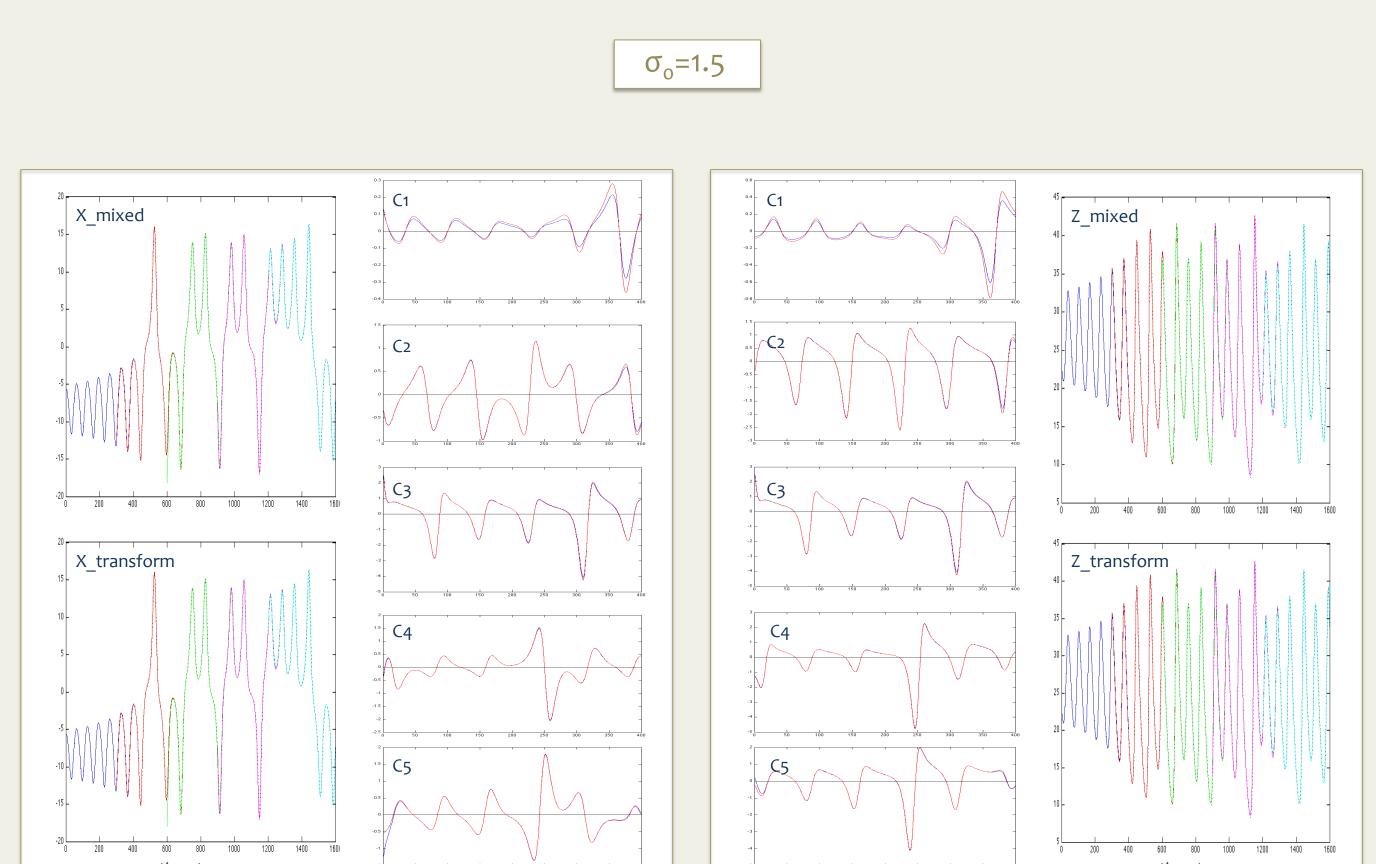
- Uses Lorenz '63 model represents convection Uses second-order Runge-Kutta scheme to solve **ODEs**
- Z variable is lognormally distributed forecast while x,y are Gaussian distributed
- Creates 'true' solution, the desired output
- Randomly generates observations to use during assimilation of each window
- Creates mixed and transform forecasts
- •Minimizes cost function, J(x)
- Updates background error covariance matrix for next forecast

Compare x,z variable differences

Y variable is not discussed – similar results to x Each cycle of forecast has a short, medium and long

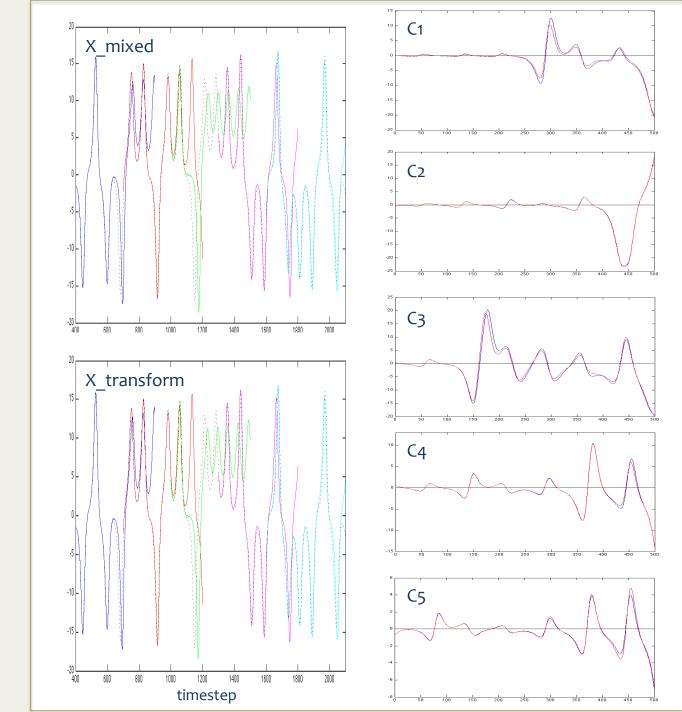


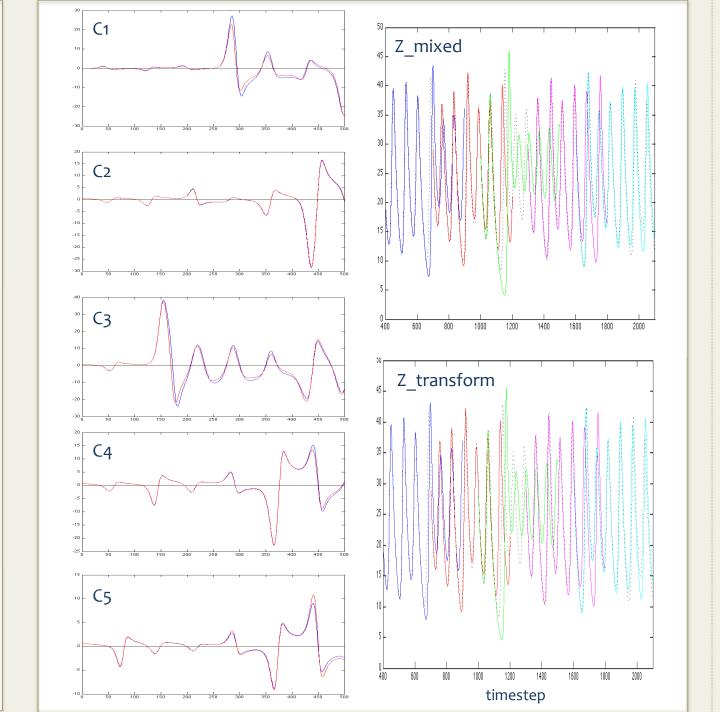


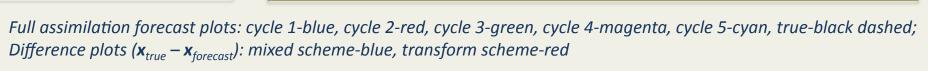


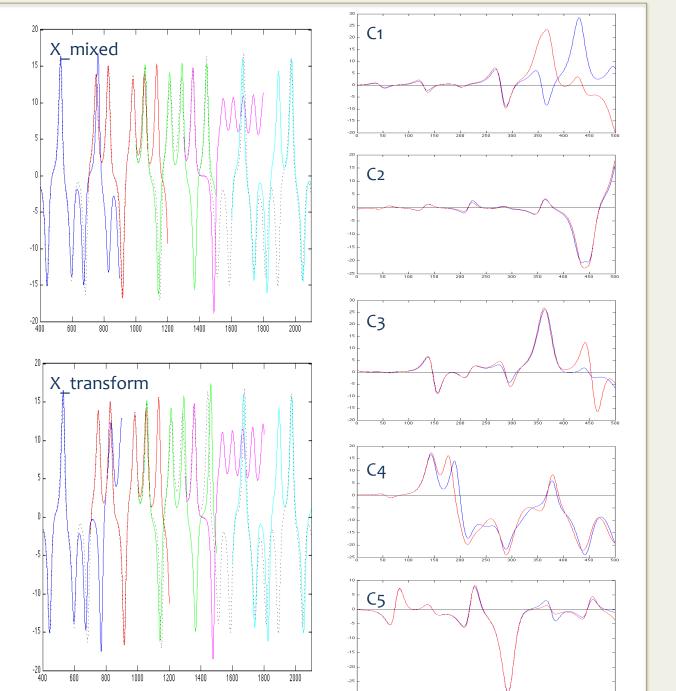
Full assimilation forecast plots: cycle 1-blue, cycle 2-red, cycle 3-green, cycle 4-magenta, cycle 5-cyan, true-black dashed; Difference plots ( $\mathbf{x}_{true} - \mathbf{x}_{forecast}$ ): mixed scheme-blue, transform scheme-red

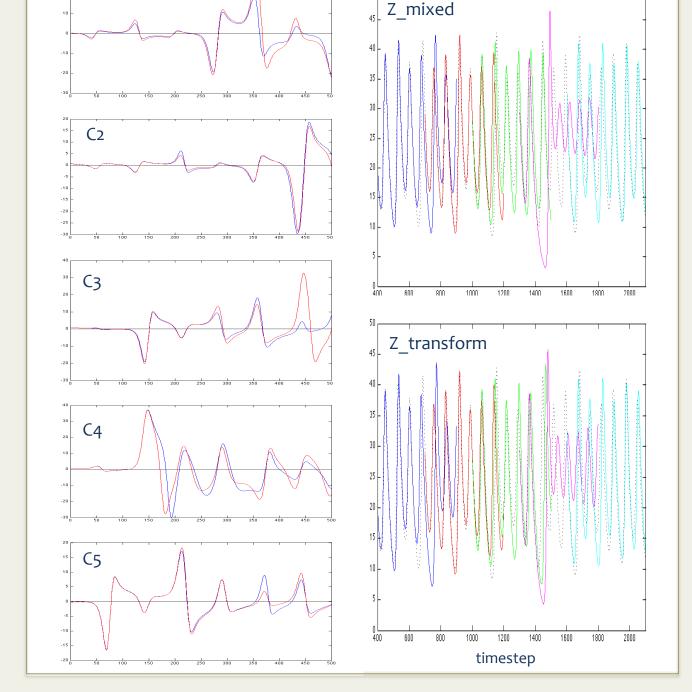
### Medium-term





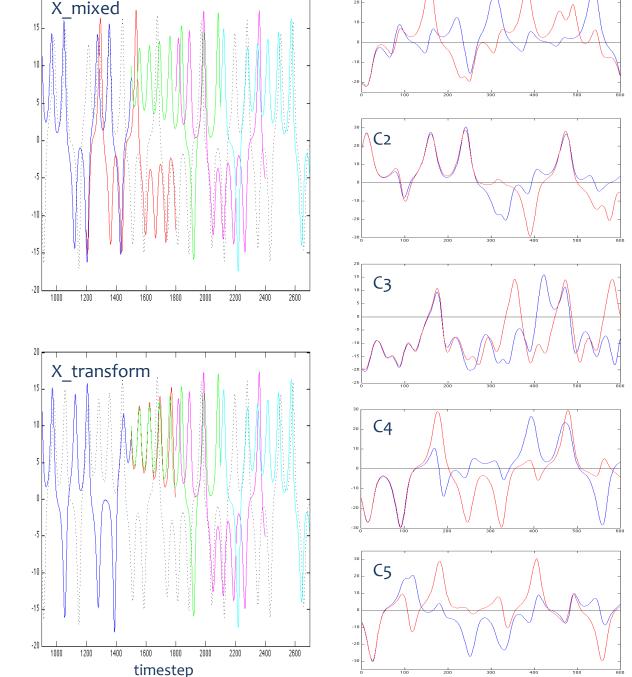


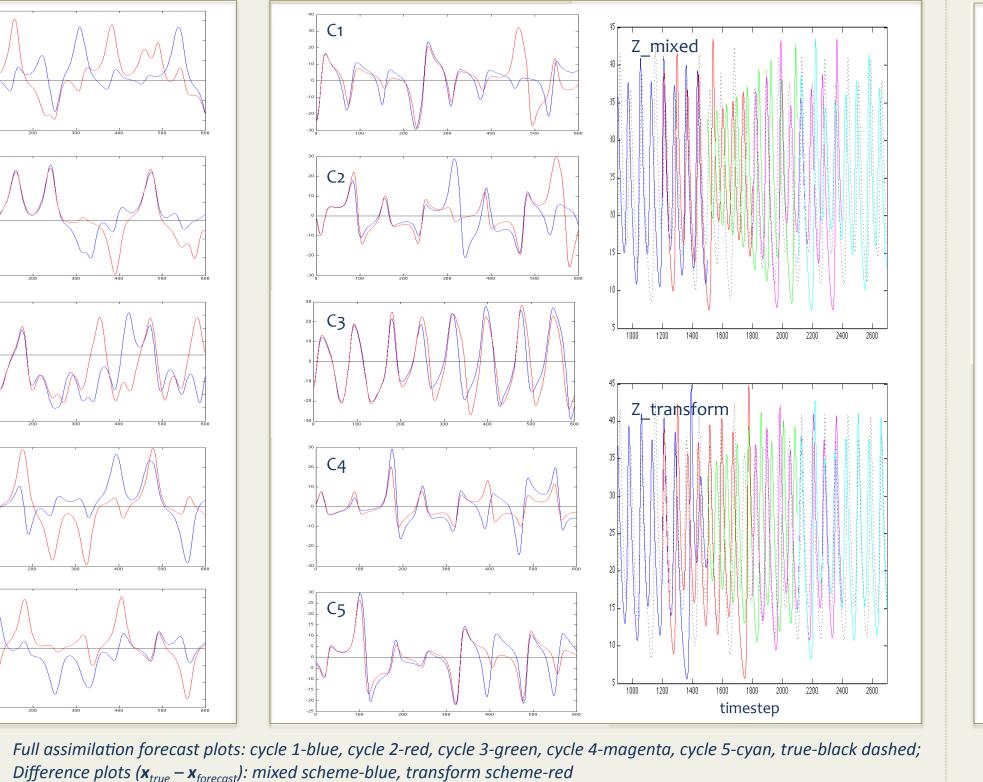


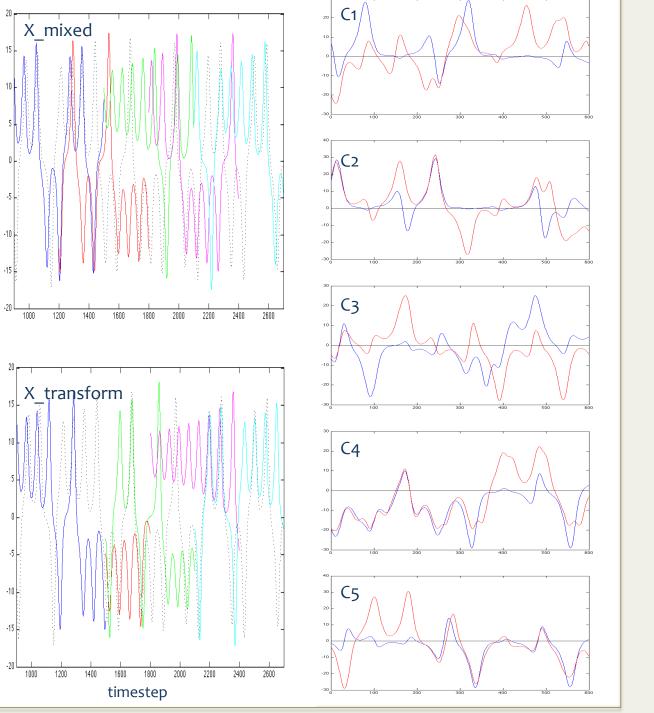


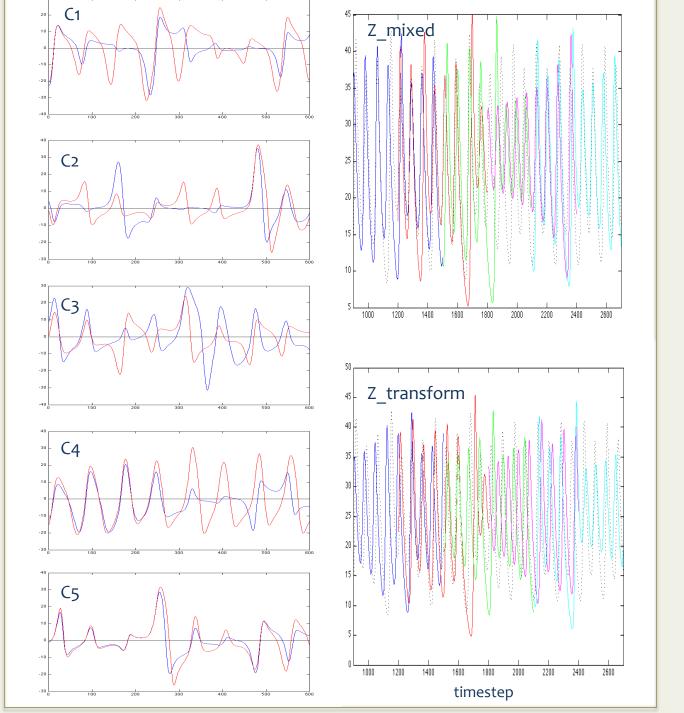
Full assimilation forecast plots: cycle 1-blue, cycle 2-red, cycle 3-green, cycle 4-magenta, cycle 5-cyan, true-black dashed; Difference plots ( $\mathbf{x}_{true} - \mathbf{x}_{forecast}$ ): mixed scheme-blue, transform scheme-red

# Long-term









Full assimilation forecast plots: cycle 1-blue, cycle 2-red, cycle 3-green, cycle 4-magenta, cycle 5-cyan, true-black dashed; Difference plots ( $\mathbf{x}_{true} - \mathbf{x}_{forecast}$ ): mixed scheme-blue, transform scheme-red

# Conclusions

#### Short

•Either scheme shows similar results

 Better initial conditions with mixed with small error obs •Amplitude not as large with mixed with large error obs

#### Medium

- •Either scheme shows similar results
- ■Mostly, mixed shows smaller peak amplitude of ~1-3 As cycles progress, errors decrease by ~60% during peaks in general

- •Either scheme is very chaotic
- •Mixed does better in X, transform does better in Z with small obs
- •Mixed does better in Z with large obs

■For less accurate observations, trends show mixed scheme is a better

 As more cycles progress, mixed becomes more accurate Changing attractors in X prove hard to get back to forecast in medium- and long-term

## Future Work

Plans for further work include rerunning this model with each assimilation scheme but with different parameters. We would like to see if fewer, but more accurate, observations can produce more correct forecasts rather than incorporating more, but less accurate, observations. Also, we would like to extend as well as shorten the window lengths and see how changing the window lengths affect the projected forecast.

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