A Nonhydrostatic Hybrid Vertical Coordinate Dynamical Core

Michael D.Toy and David A. Randall -- *Department of Atmospheric Science, Colorado State University*

Introduction

We have developed a nonhydrostatic atmospheric dynamical core which takes advantage of an isentropic vertical coordinate in the free atmosphere and a terrainfollowing, height-based coordinate near the surface. Use of such a hybrid vertical coordinate has previously been developed for hydrostatic models. Our goal here is to apply similar methods to a high-resolution cloud resolving model in which nonhydrostatic effects are important.

One of the main challenges with isentropic coordinates is handling massless layers and preventing coordinate surfaces from crossing each other. We have experienced these issues in our model and are working to solve them. So far we have made progress by experimenting with an upstream advection scheme in the continuity equation. Our goal is to obtain longer runs with the hybrid coordinate, as we have done with the model run in pure *σ*-coordinate mode as shown in Figure 6. $\dot{\eta} = D \eta / D t$ **Figure 1.1** Preventing coordinate surfaces from crossing each

We note here that other work in nonhydrostatic modeling with a hybrid vertical coordinate has been performed using a regridding method for handling the vertical coordinate, e.g., He (2002). In our model we follow the approach of Konor and Arakawa (1997) to define the vertical coordinate.

We have had success with a previous *σ*-coordinate version of our nonhydrostatic model in simulating phenomena at various scales -- from a sheared rising thermal with a capping stable layer to the development of a synoptic scale, baroclinic disturbance on a *β*-plane. These results are shown in Figure 7.

The vertical finite difference scheme is based on the fully elastic system of Euler equations. It conserves mass and total energy is conserved with a second-order, centered advection scheme. An integral constraint on the circulation developed around a contour of surface topography is also satisfied. These features are important as we intend to use the dynamical core for long term global climate simulations.

> *x z* Vertical Index *k* - 3⁄2 *k* - ½ *w*, *θ*, *Φ k* - 1 *k* + ½ *w*, *θ*, *Φ* $k+1 - - - - -$ k – – – – – V, m $k + \frac{3}{2}$

 $V =$ horizontal velocity $w =$ vertical velocity $m =$ pseudo-density θ = potential temperature Φ = geopotential height

Figure 1: Vertical staggering of the prognostic variables.

First, we choose the form of $g(\sigma)$ as shown below, where *r* is a constant which controls how quickly the transition to *θ*-coordinates occurs:

Vertical grid

We use the Charney-Phillips grid in which potential temperature and mass are staggered. The staggering of the prognostic variables is shown in Figure 1.

Challenges and Goals

Figure 5: Potential temperature field at $t = 1$ hour: a) Terrain-following height-based coordinate throughout domain, and b) hybrid coordinate.

Vertical coordinate

Following Konor and Arakawa (1997) we define the vertical coordinate as a prescribed function of height and potential temperature. Since our model is nonhydrostatic we use geometric height instead of pressure as the height metric.

The vertical coordinate (*η*) is defined as:

The transition of *η* from terrain-following to potential temperature coordinates requires:

 $\overline{}$ m)

$$
\eta = F(\theta, \sigma) = f(\sigma) + g(\sigma) \theta, \qquad (1)
$$

where $\sigma = \frac{2}{7} \frac{8.5}{7}$, z_s = surface height, and z_T = model top height. $\frac{z - z_{S}}{z_{T} - z_{S}}$ $, z_S$ = surface height, and z_T = model top height.

$$
g(\sigma) \to 0 \quad \text{as } \sigma \to 0,
$$

$$
f(\sigma) \to 0
$$
 and $g(\sigma) \to 1$ as $\sigma \to 1$.

$$
g(\sigma) = 1 - (1 - \sigma)^r
$$

In order to guarantee that the vertical coordinate be monotonic, $f(\sigma)$ is determined from the following equation where θ_{\min} and $\left(\frac{\partial \theta}{\partial \sigma}\right)_{\min}$ are suitably chosen minimum values of potential temperature and static stability respectively: θ $_{\rm min}$ and $\left(\frac{\partial \theta}{\partial \sigma}\right)_{\rm min}$ ar

$$
\frac{df}{d\sigma} + \frac{dg}{d\sigma} \theta_{\min} + g \left(\frac{\partial \theta}{\partial \sigma} \right)_{\min} = 0.
$$

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M5, (h) N