

Long evaluations of cloud in SAM at the SGP

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Fort Collins, July 2008

Project outline

- ▶ **Goal: to evaluate cloud in SAM**
- ▶ Using 3-year runs
- ▶ Evaluating POC (aka cloud fraction) against ARSCL
 - ▶ with and without temporal averaging
- ▶ Using observations to define cloud-occurrence in model
 - ▶ via radar-simulator & lidar-proxy

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Model runs

- ▶ 3-year runs of SAM (1999–2002) at SGP, forced with ARM data (M. Zhang, J. Lin, S. Xie, et al)
- ▶ Comparing results of 2D, 2D+IPHOC and 3D configurations
 - ▶ 2D: $32 \times 1 \times 28$; $\Delta x = 4$ km (MMF-like)
 - ▶ 3D: $128 \times 128 \times 64$; $\Delta x = \Delta y = 500$ m

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Model runs

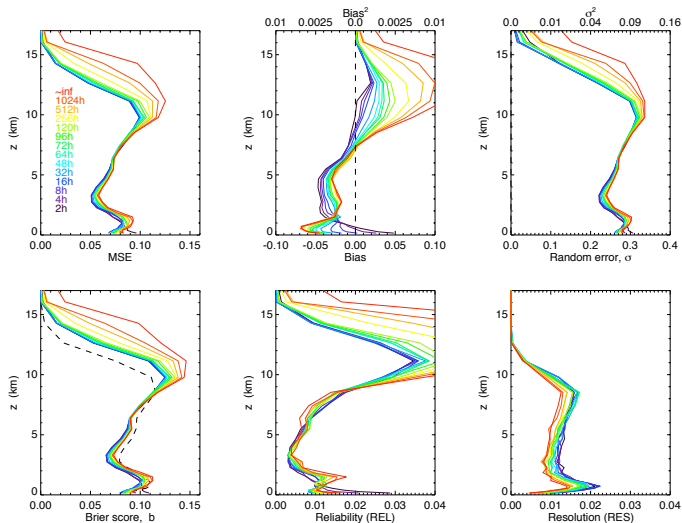
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Performance metrics

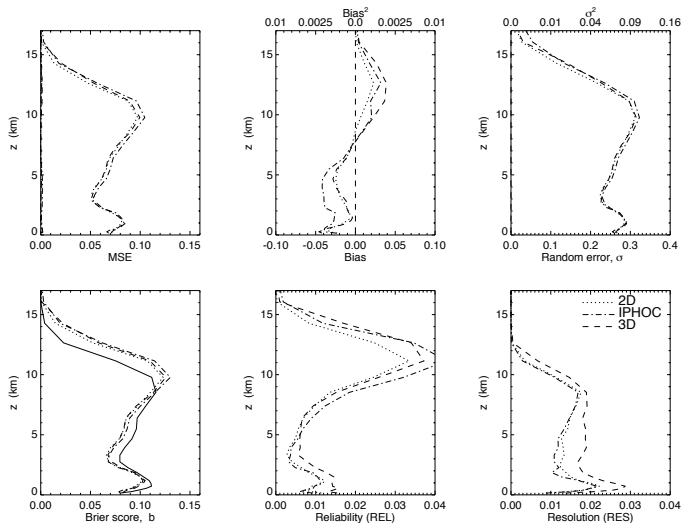
▶ $MSE = bias^2 + random^2$

▶ $b = reliability - resolution + uncertainty$

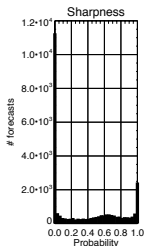
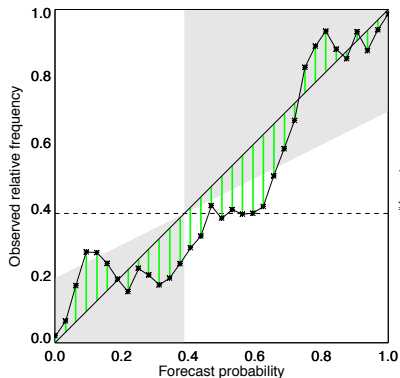
2D cloud-errors: $\tau_T \in \{2, 4, 8, 16, \dots, 512, 1024, \text{inf}\}$



Cloud errors in 2D, 2D+IPHOC & 3D runs; ($\tau_T = 24$)



Brier Score, b = limiting case of MSE

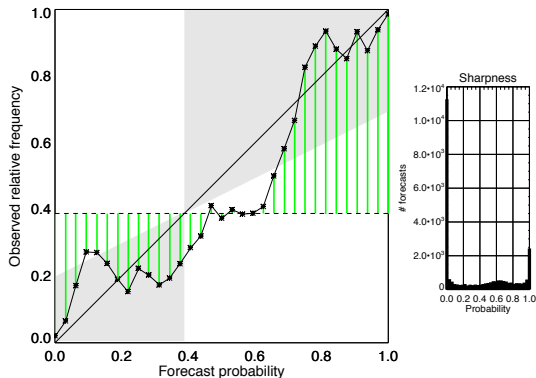


$$b = \frac{1}{N} \sum_{i=1}^N (p_i - o_i)^2$$

$b = \text{reliability} - \text{resolution} + \text{uncertainty},$

$$= \frac{1}{N} \sum_{k=1}^K n_k (p_k - \bar{o}_k)^2 - \frac{1}{N} \sum_{k=1}^K n_k (\bar{o}_k - \bar{o})^2 + \bar{o}(1 - \bar{o})$$

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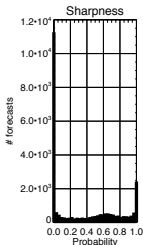
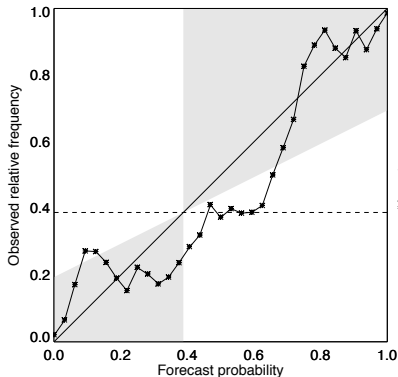


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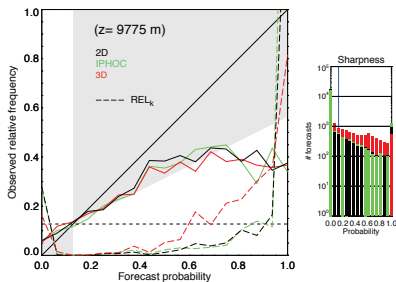
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Measures variability of observations only; max at $\bar{o} = \frac{1}{2}$.

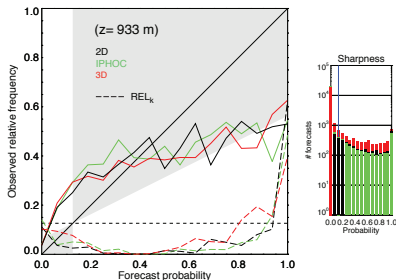
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Weightings of conditional biases (reliability)

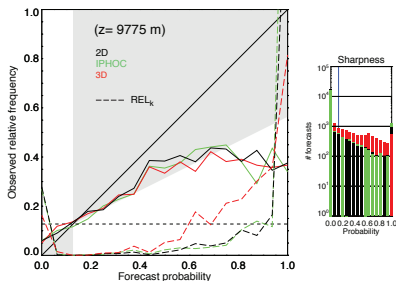


- ▶ All over-predict most p
- ▶ 3D has least bias due to extreme p & most for mid-high p
- ▶ IPHOc most biased :: $p = 1$ contributions

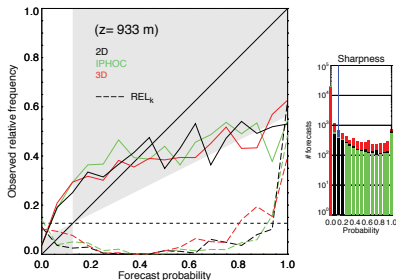


- ▶ All under-predict low p
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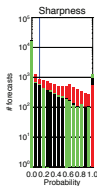
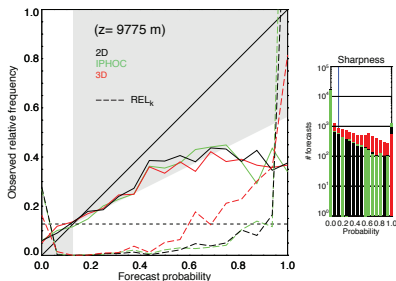


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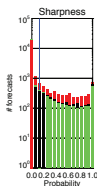
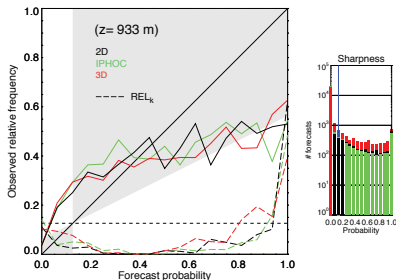


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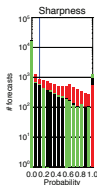
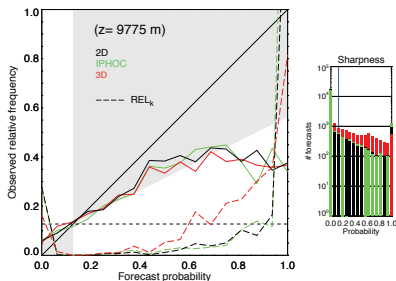


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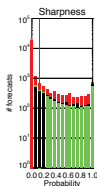
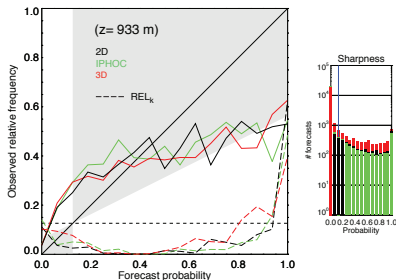


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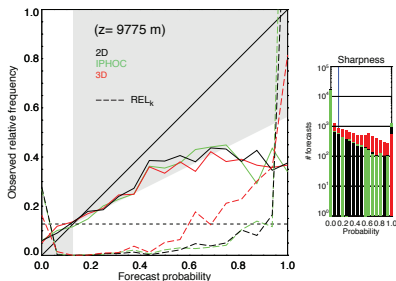


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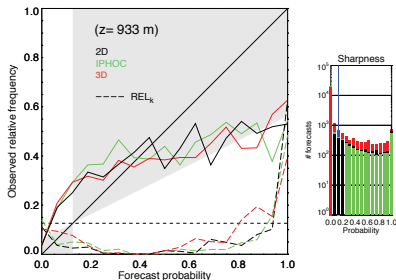


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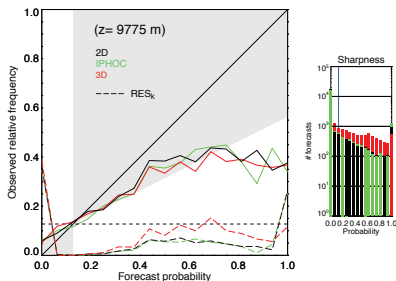


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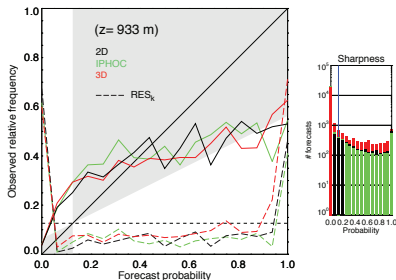


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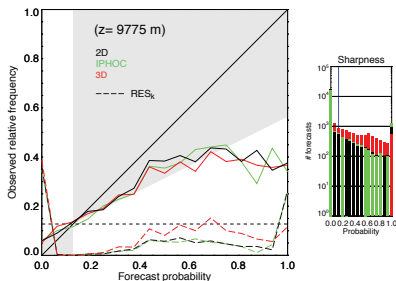


- ▶ Most contributions for $p = 0, 1$
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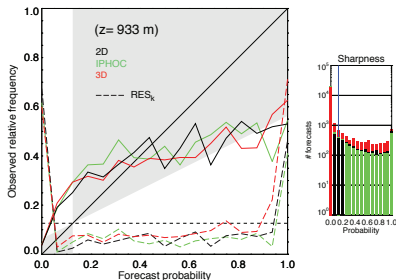


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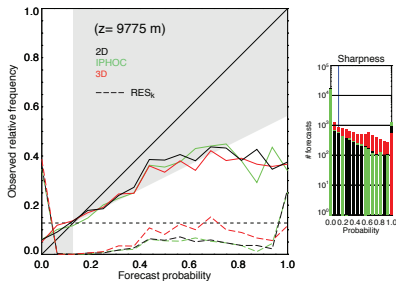


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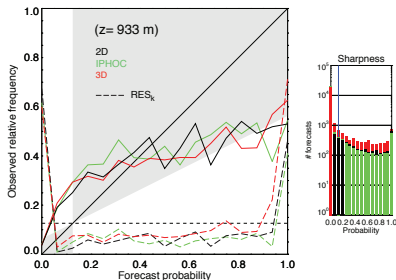


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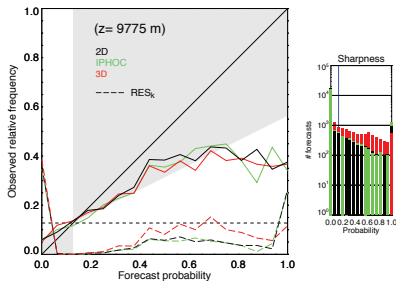


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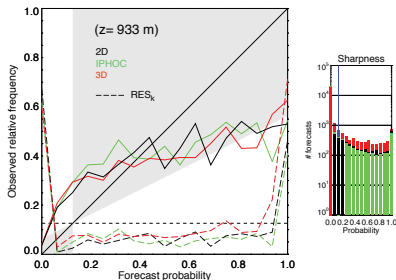


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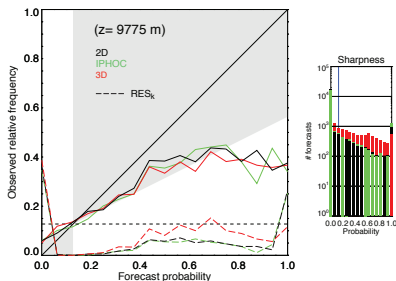


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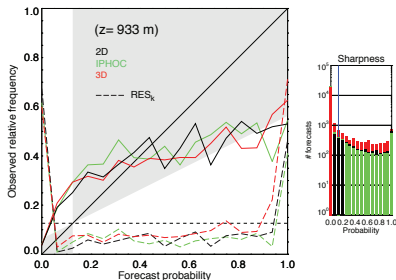


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- ▶ Small bias \implies model well calibrated (overall)
- ▶ Range in $\{\text{RES}, \text{RES}\}$ for 2D-3D \sim range seen over τ_T
 \implies significant differences between configurations
- ▶ Conditional bias & timing best for low cloud
- ▶ 3D has best timing at all z , but most conditional bias in PBL

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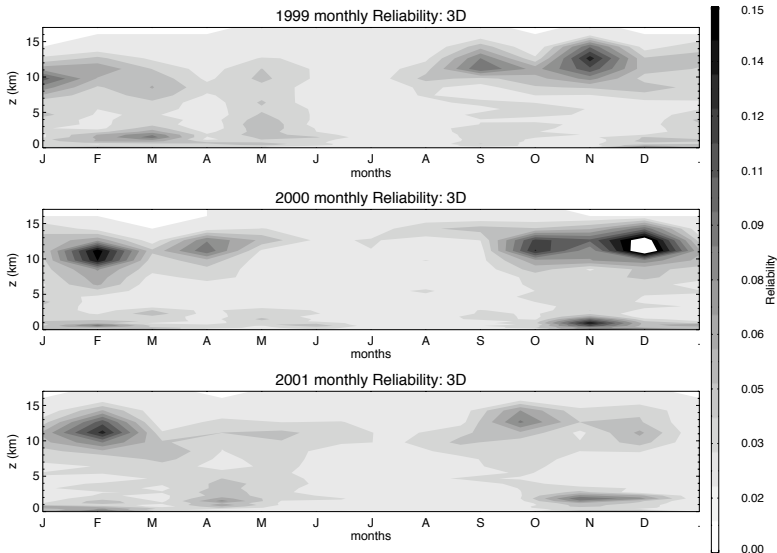
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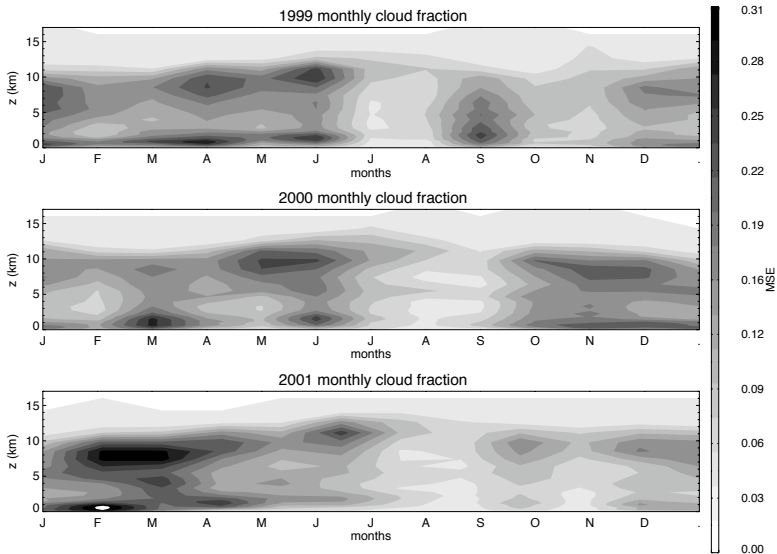
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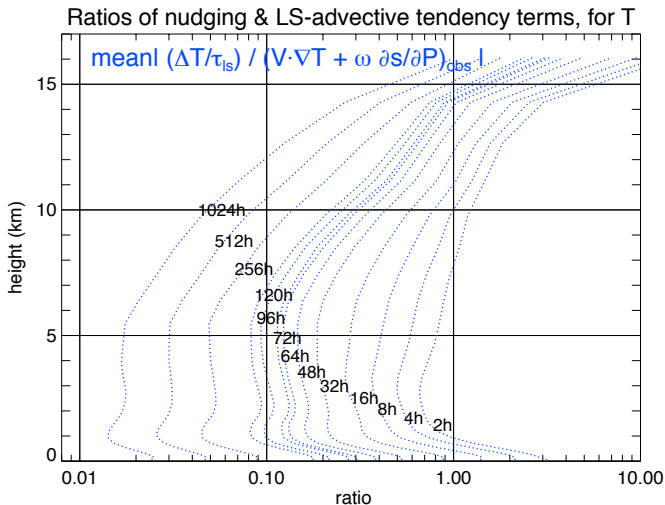
When do differences in performance occur?



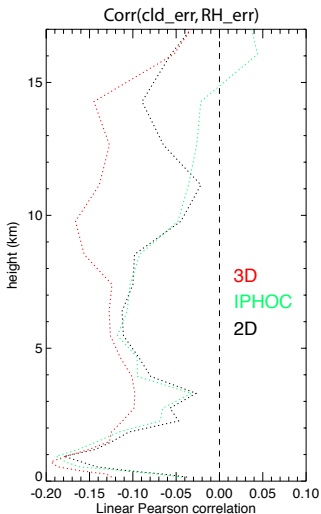
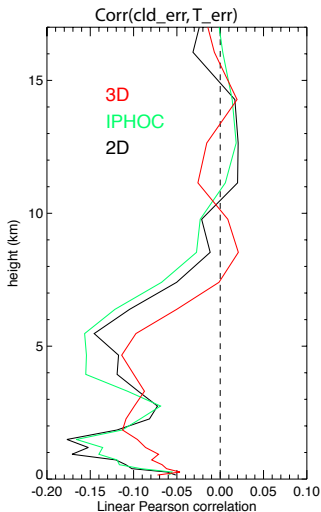
Extra slide: ARSCL monthly cloud fraction



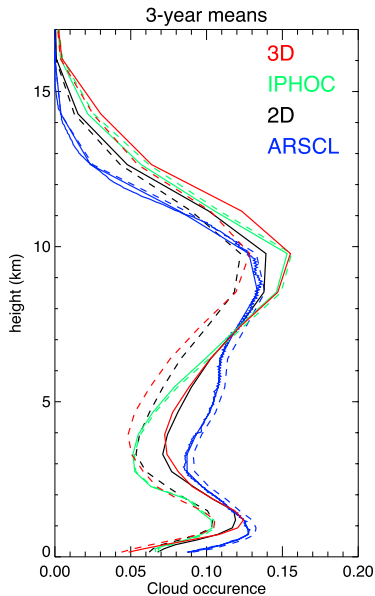
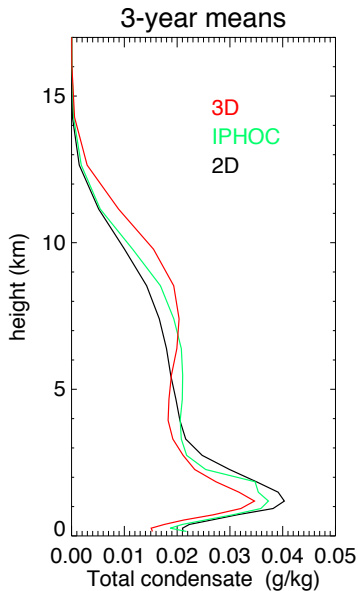
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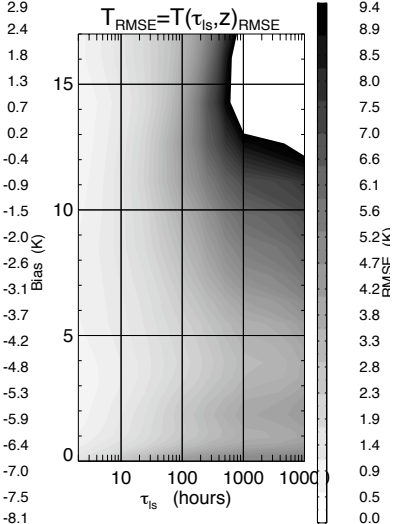
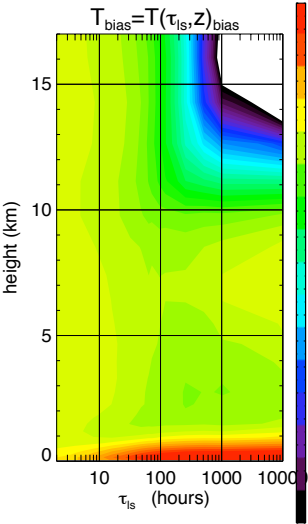


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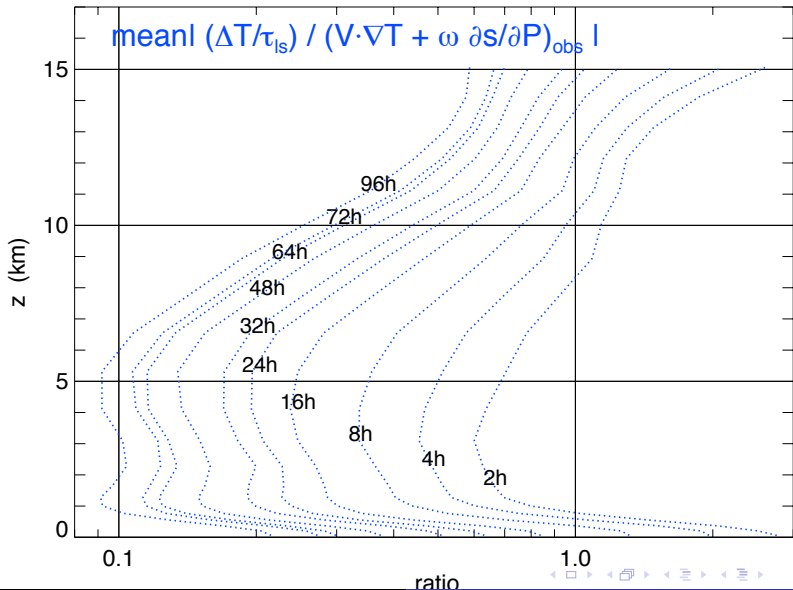


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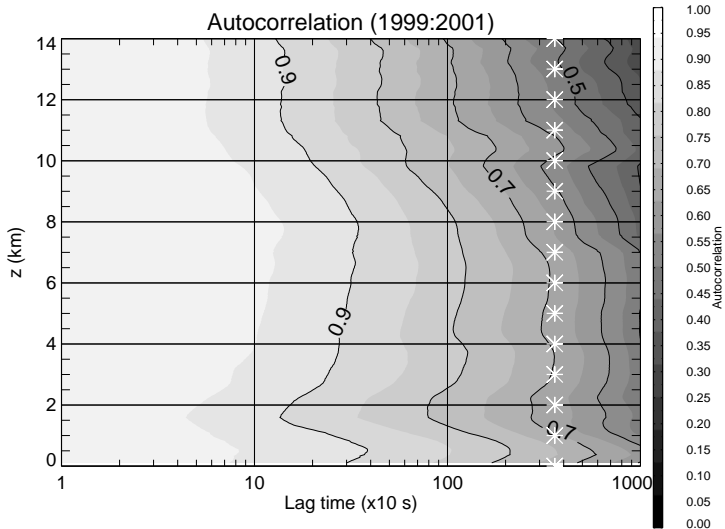
RAD_CAM



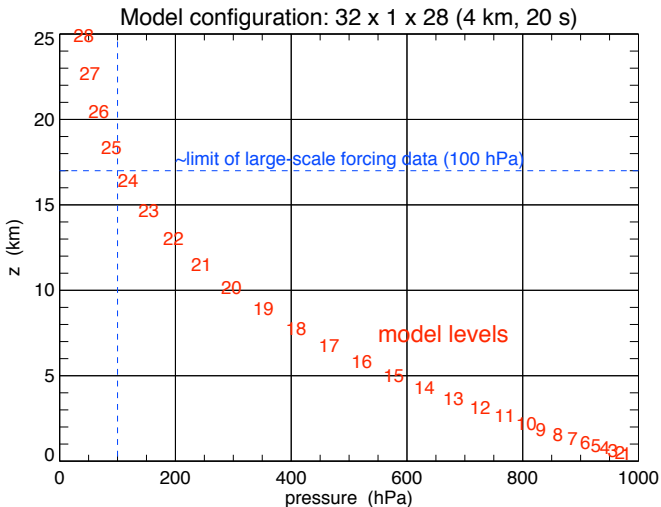
Extra slide: Ratios of nudging & advective tendency of T



Extra slide: ARSCL: correlogram



Extra slide: model grid



/mac_home/phenderson/ld/pros/meta_nudge.pro

/Clouds/pwh/results/ld_out/meta_nudge.ps.gz